## The EFD thing

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and Nigel for the title

## Ever found too many coordinate systems?

Which elliptic curve coordinate system

is the fastest for addition, doubling, ...?

## Ever found too many coordinate systems?

Which elliptic curve coordinate system

- is the fastest for addition, doubling, ...?
- is the slowest for addition, doubling,...?

## Ever found too many coordinate systems?

Which elliptic curve coordinate system

- is the fastest for addition, doubling, ...?
- is the fastest for re-addition?
- is the fastest for unified group operations?
- needs the fewest registers?
- is the best for single-scalar multiplication?
- is the best for multi-scalar multiplication?
- is the best for batch verification of signatures?
- etc.

... and which formulas are the best for a given system?

## **Projective Coordinates**

$$P=(X_1:Y_1:Z_1),\,Q=(X_2:Y_2:Z_2),\,P\oplus Q=(X_3:Y_3:Z_3)$$
 on  $E:Y^2Z=X^3+a_4XZ^2+a_6Z^3;\,(x,y)\sim (X/Z,Y/Z)$ 

Addition:  $P \neq \pm Q$ 

$$A = Y_2 Z_1 - Y_1 Z_2, B = X_2 Z_1 - X_1 Z_2, A = a_4 Z_1^2 + 3X_1^2, B = Y_1 Z_1,$$

$$C = A^2 Z_1 Z_2 - B^3 - 2B^2 X_1 Z_2$$

$$X_3 = BC, Z_3 = B^3 Z_1 Z_2$$

$$Y_3 = A(B^2 X_1 Z_2 - C) - B^3 Y_1 Z_2,$$

Doubling  $P = Q \neq -P$ 

$$A = a_4 Z_1^2 + 3X_1^2, B = Y_1 Z_1,$$

$$C = X_1 Y_1 B, D = A^2 - 8C$$

$$X_3 = 2BD, Z_3 = 8B^3$$
.

$$Y_3 = A(4C - D) - 8Y_1^2 B^2$$

- No inversion is needed good for most implementations
- General ADD: 12M+2S
- **DBL:** 7M+5S
- Fast . . . but very different performance of ADD and DBL

## **Jacobian Coordinates**

$$P=(X_1:Y_1:Z_1),\,Q=(X_2:Y_2:Z_2),\,P\oplus Q=(X_3:Y_3:Z_3)$$
 on  $Y^2=X^3+a_4XZ^4+a_6Z^6$ ;  $(x,y)\sim (X/Z^2,Y/Z^3)$ 

Addition:  $P \neq \pm Q$ 

$$A = X_1 Z_2^2, B = X_2 Z_1^2, C = Y_1 Z_2^3, A = Y_1^2, B = Z_1^2$$

$$X_3 = 2(-E^3 - 2AE^2 + F^2)$$

$$Z_3 = E(Z_1 + Z_2)^2 - Z_1^2 - Z_2^2$$

$$Y_3 = 2(-CE^3 + F(AE^2 - X_3)),$$

Doubling  $P = Q \neq -P$ 

$$A = Y_1^2, B = Z_1^2$$

$$D = Y_2 Z_1^3, E = B - A, F = D - C$$
  $C = 4X_1 A, D = 3X_1^2 + a_4 B^2$ 

$$X_3 = -2C + D^2$$

$$Z_3 = (Y_1 + Z_1)^2 - A - B$$

$$Y_3 = -8A^2 + D(C - X_3)$$
.

- General ADD: 11M+5S
- mixed ADD  $(\mathcal{J} + \mathcal{A} = \mathcal{J})$ : 8M+3S
- DBL: 3M+7S (one M by  $a_4$ ); for  $a_4 = -3$ : 3M+5S

− p. 4

## **Chudnovsky Jacobian Coordinates**

$$P=(X_1:Y_1:Z_1:Z_1^2:Z_1^3),\,Q=(X_2:Y_2:Z_2:Z_2^2:Z_2^3),\ P\oplus Q=(X_3:Y_3:Z_3:Z_3^2:Z_3^3) \text{ on } Y^2=X^3+a_4XZ^4+a_6Z^6;\ (x,y)\sim (X/Z^2,Y/Z^3)$$

Addition:  $P \neq \pm Q$ 

$$A = X_1 Z_2^2, B = X_2 Z_1^2, C = Y_1 Z_2^3,$$

$$D = Y_2 Z_1^3, E = B - A, F = D - C$$

$$X_3 = 2(-E^3 - 2AE^2 + F^2)$$

$$Z_3 = E(Z_1 + Z_2)^2 - Z_1^2 - Z_2^2$$

$$Y_3 = 2(-CE^3 + F(AE^2 - X_3)),$$

$$Z_3^2, Z_3^3$$
,

Doubling  $P = Q \neq -P$ 

$$A = Y_1^2,$$

$$C = 4X_1A, D = 3X_1^2 + a_4(Z_1^2)^2$$

$$X_3 = -2C + D^2$$

$$Z_3 = (Y_1 + Z_1)^2 - A - Z_1^2$$

$$Y_3 = -8A^2 + D(C - X_3)$$

$$Z_3^2, Z_3^3$$

- General ADD: 10M+4S
- mixed ADD  $(\mathcal{J} + \mathcal{A} = \mathcal{J})$ : 8M+3S
- DBL:3M+7S (one M by  $a_4$ )<sub>http://hyperelliptic.org/EFD</sub>

# ...and with extra feature: SCA resistance...

## **Montgomery Form**

#### Generalized to arbitrary multiples

$$[n]P = (X_n:Y_n:Z_n), [m]P = (X_m:Y_m:Z_m)$$
 with known difference  $[m-n]P$  on  $E_M:By^2=x^3+Ax^2+x$ 

Addition:  $n \neq m$ 

$$X_{m+n} = Z_{m-n} ((X_m - Z_m)(X_n + Z_n) + (X_m + Z_m)(X_n - Z_n))^2$$
  
$$Z_{m+n} = X_{m-n} ((X_m - Z_m)(X_n + Z_n) - (X_m + Z_m)(X_n - Z_n))^2$$

Doubling: n = m

$$4X_n Z_n = (X_n + Z_n)^2 - (X_n - Z_n)^2,$$

$$X_{2n} = (X_n + Z_n)^2 (X_n - Z_n)^2,$$

$$Z_{2n} = 4X_n Z_n ((X_n - Z_n)^2 + ((A+2)/4)(4X_n Z_n)).$$

An addition takes 4M and 2S whereas a doubling needs only 3M and 2S. Order is divisible by 4.

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## **Side-channel atomicity**

- Chevallier-Mames, Ciet, Joye 2004
  Idea: build group operation from identical blocks.
- Each block consists of:

1 multiplication, 1 addition, 1 negation, 1 addition;

fill with cheap dummy additions and negations ADD  $(A + \mathcal{J})$  needs 11 blocks DBL  $(2\mathcal{J})$  needs 10 blocks

$ADD_9$	$ADD_{10}$	$ADD_{11}$	$DBL_1$	$DBL_2$	$DBL_3$	$DBL_4$	$DBL_5$	

- Requires that M and S are indistinguishable from their traces.
- No protection against fault attacks.

## **Unified Projective coordinates**

- Brier, Joye 2002 Idea: unify how the slope is computed.
- improved in Brier, Déchène, and Joye 2004

$$\lambda = \frac{(x_1 + x_2)^2 - x_1 x_2 + a_4 + y_1 - y_2}{y_1 + y_2 + x_1 - x_2}$$

$$= \begin{cases} \frac{y_1 - y_2}{x_1 - x_2} & (x_1, y_1) \neq \pm (x_2, y_2) \\ \frac{3x_1^2 + a_4}{2y_1} & (x_1, y_1) = (x_2, y_2) \end{cases}$$

Multiply numerator & denominator by  $x_1 - x_2$  to see this.

- Proposed formulae can be generalized to projective coordinates.
- Some special cases may occur, but with very low probability, e.g.  $x_2 = y_1 + y_2 + x_1$ . Alternative equation for this case.

## Jacobi intersection and quartic

- Liardet and Smart CHES 2001: Jacobi intersection
- Billet and Joye AAECC 2003: Jacobi-Model

$$E_J: Y^2 = \epsilon X^4 - 2\delta X^2 Z^2 + Z^4.$$

$$X_{3} = X_{1}Z_{1}Y_{2} + Y_{1}X_{2}Z_{2}$$

$$Z_{3} = (Z_{1}Z_{2})^{2} - \epsilon(X_{1}X_{2})^{2}$$

$$Y_{3} = (Z_{3} + 2\epsilon(X_{1}X_{2})^{2})(Y_{1}Y_{2} - 2\delta X_{1}X_{2}Z_{1}Z_{2}) + 2\epsilon X_{1}X_{2}Z_{1}Z_{2}(X_{1}^{2}Z_{2}^{2} + Z_{1}^{2}X_{2}^{2}).$$

- Unified formulas need 10M+3S+D+2E
- **•** Can have  $\epsilon$  or  $\delta$  small
- ▶ Needs point of order 2; for  $\epsilon = 1$  the group order is divisible by 4.

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## **Hessian curves**

$$E_H: X^3 + Y^3 + Z^3 = cXYZ.$$

Addition: 
$$P \neq \pm Q$$
 Doubling  $P = Q \neq -P$   $X_3 = X_2Y_1^2Z_2 - X_1Y_2^2Z_1$   $X_3 = Y_1(X_1^3 - Z_1^3)$   $Y_3 = X_1^2Y_2Z_2 - X_2^2Y_1Z_1$   $Y_3 = X_1(Z_1^3 - Y_1^3)$   $Z_3 = X_2Y_2Z_1^2 - X_1Y_1Z_2^2$   $Z_3 = Z_1(Y_1^3 - X_1^3)$ 

- Curves were first suggested for speed
- Joye and Quisquater suggested Hessian Curves for unified group operations using

$$[2](X_1:Y_1:Z_1)=(Z_1:X_1:Y_1)\oplus(Y_1:Z_1:X_1)$$

- Unified formulas need 12M.
- Needs point of order 3.

## There is help!

## Explicit-Formulas Database www.hyperelliptic.org/EFD

## **Explicit-Formulas Database**

	System	Cost of doubling
_	Projective	5M+6S+1D; EFD
	Projective if $a_4 = -3$	7M+3S; EFD
	Hessian	6M+3S; see Joye/Quisquater '01
	Jacobi quartic	1M+9S+1D; see Billet/Joye '01
	Jacobian	1M+8S+1D; EFD
	Jacobian if $a_4 = -3$	3M+5S; see DJB '01
	Jacobi intersection	3M+4S; see Liardet/Smart '01
	Doche/Icart/Kohel	2M+5S+2D; see Doche/Icart/Kohel '06

- All formulas human readable and computer verifiable.
- Several speed-ups only in EFD!
- Correct formulas only in EFD!
- Will extend EFD to characteristic 2 soon.

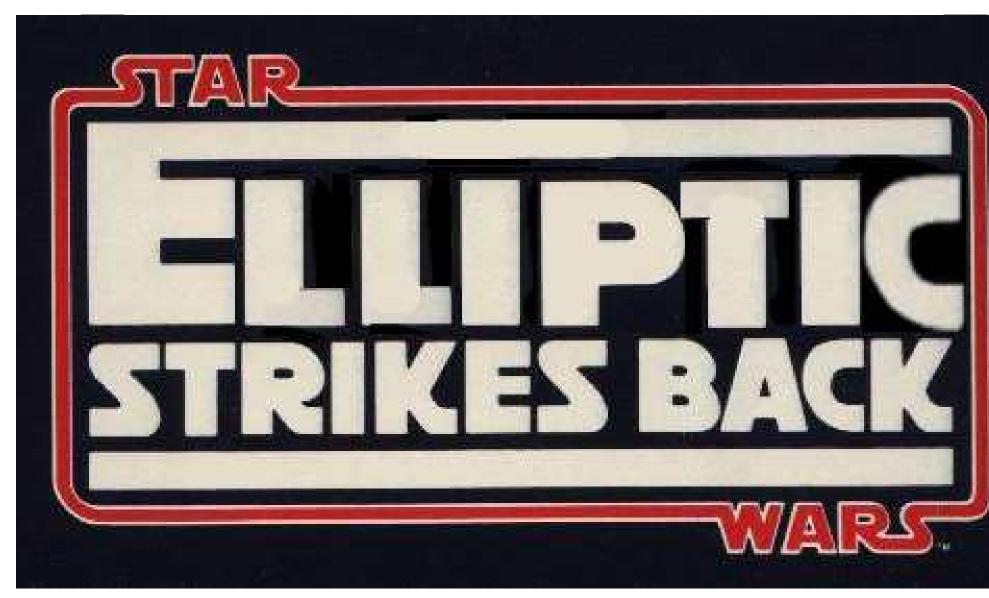
## Elliptic vs Hyperelliptic

More and more papers say: Genus-2 hyperelliptic curves are better than elliptic curves!

- Special families of genus-2 curves in characteristic 2 faster than ECC.
- Generalization of Montgomery in odd characteristic
  - Gaudry: Genus-2 Montgomery-style formulas for nP in large characteristic.
  - Bernstein ECC 2006 "New Diffie-Hellman speed record" (with HECC)
  - Gaudry, ECC 2007: "Important speed-up."
- Special base points for pairings.

Plan to include hyperelliptic curves in EFD.

## But time has come ...



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k field of odd characteristic.

$$x^2 + y^2 = 1 + dx^2y^2$$

is an elliptic curve for  $d \neq 0, 1$ .

$$P + Q = \left(\frac{x_P y_Q + y_P x_Q}{1 + dx_P x_Q y_P y_Q}, \frac{y_P y_Q - x_P x_Q}{1 - dx_P x_Q y_P y_Q}\right).$$

- ullet Neutral element is (0,1), this is an affine point!
- $-(x_P, y_P) = (-x_P, y_P).$

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Unified group operations!

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$$P + Q = \left(\frac{x_{P}y_{Q} + y_{P}x_{Q}}{1 + dx_{P}x_{Q}y_{P}y_{Q}}, \frac{y_{P}y_{Q} - x_{P}x_{Q}}{1 - dx_{P}x_{Q}y_{P}y_{Q}}\right).$$

$$A = Z_{P} \cdot Z_{Q}; B = A^{2}; C = X_{P} \cdot X_{Q}; D = Y_{P} \cdot Y_{Q};$$

$$E = d \cdot C \cdot D; F = B - E; G = B + E;$$

$$X_{P+Q} = A \cdot F \cdot ((X_{P} + Y_{P}) \cdot (X_{Q} + Y_{Q}) - C - D);$$

$$Y_{P+Q} = A \cdot G \cdot (D - C); Z_{P+Q} = F \cdot G.$$

k field of odd characteristic.

$$x^2 + y^2 = 1 + dx^2y^2$$

is an elliptic curve for  $d \neq 0, 1$ .

$$P + Q = \left(\frac{x_{P}y_{Q} + y_{P}x_{Q}}{1 + dx_{P}x_{Q}y_{P}y_{Q}}, \frac{y_{P}y_{Q} - x_{P}x_{Q}}{1 - dx_{P}x_{Q}y_{P}y_{Q}}\right).$$

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$$X_{P+Q} = A \cdot F \cdot ((X_{P} + Y_{P}) \cdot (X_{Q} + Y_{Q}) - C - D);$$

$$Y_{P+Q} = A \cdot G \cdot (D - C); Z_{P+Q} = F \cdot G.$$

Needs 10M + 1S + 1D + 7A.

## **Fastest unified formulae**

System	Cost of unified addition-or-doubling
Projective	11M+6S+1D; see Brier/Joye '03
Projective if $a_4 = -1$	13M+3S; see Brier/Joye '02
Jacobi intersection	13M+2S+1D; see Liardet/Smart '01
Jacobi quartic	10M+3S+1D; see Billet/Joye '01
Hessian	12M; see Joye/Quisquater '01
Edwards ( $c = 1$ )	10M+1S+1D

- Exactly the same formulae for doubling (no re-arrangement like in Hessian; no if-else)
- No exceptional cases if d is not a square. Formulae correct for all affine inputs (incl. (0, c), P + (-P)); formulae are complete!

## Very fast doubling formulae

System	Cost of doubling
Projective	5M+6S+1D; EFD
Projective if $a_4 = -3$	7M+3S; EFD
Hessian	6M+3S; see Joye/Quisquater '01
Jacobi quartic	1M+9S+1D; see Billet/Joye '01
Jacobian	1M+8S+1D; EFD
Jacobian if $a_4 = -3$	3M+5S; see DJB '01
Jacobi intersection	3M+4S; see Liardet/Smart '01
Edwards ( $c = 1$ )	3M+4S;
Doche/Icart/Kohel	2M+5S+2D; see Doche/Icart/Kohel '06

Edwards fastest for general curves, no D.

## **Fastest addition formulae**

	System	Cost of addition
-	Doche/Icart/Kohel	12M+5S+1D; see Doche/Icart/Kohel '06
	Jacobian	11M+5S; EFD
	Jacobi intersection	13M+2S+1D; see Liardet/Smart '01
	Projective	12M+2S; HECC
	Jacobi quartic	10M+3S+1D; see Billet/Joye '03
	Hessian	12M; see Joye/Quisquater '01
	Edwards ( $c = 1$ )	10M+1S+1D

- Faster than Jacobian-3 etc. for single-scalar multiplication, multi-scalar multiplication, etc.
- Complete addition formulas: code-size advantage and SCA resistance.
- More at Asiacrypt 2007.

